

A nonlinear uncertain normal form for interval observers

D. Boutat, A. Benali, and N. Ramdani

Université d'Orléans, ENSI Bourges, PRISME, 18000 Bourges,
France.

This talk deals with necessary and sufficient conditions to guarantee the existence of a transformation of a class of single output nonlinear uncertain dynamical systems into a nonlinear uncertain normal form (NUNF). This last form, allows us to design the so-called practical interval observer to estimate the state with a bounded estimation error.